

## Strings and Governors

**General Configuration:** A light and smooth string of length  $L$  is attached to a vertical pole. One end of the string is attached to point  $A$ , which is fixed at the top of the pole, and another end to point  $B$ ,  $h$  units of length under  $A$ . A ring of mass  $m$  has been threaded into the string at position  $P$ , so  $AP$  is  $l_1$  units of length, and  $PB$  is  $l_2$ .  $AP$  is at angle  $\theta_1$  to the vertical, and  $PB$  at  $\theta_2$ .

Point  $P$  describes a horizontal circle of radius  $r$  in Uniform Circular Motion at angular speed of  $\omega$ . While  $A$  is always fixed,  $P$  and  $B$  can be loose in some configurations. When  $B$  is loose, a mass  $M$  will be attached to it. The tension on  $AP$  is  $T_1$  and that on  $PB$  is  $T_2$ .

**Strings of Equal Length:** Let  $l = l_1 = l_2$ , and  $\theta = \theta_1 = \theta_2$ ;  $P$  and  $B$  are fixed.  $r = l \sin \theta$ ,  $h = 2l \cos \theta$ .

$$\text{Horizontal: } T_1 \sin \theta + T_2 \sin \theta = mr\omega^2 = ml \sin \theta \cdot \omega^2, \quad T_1 + T_2 = ml\omega^2 \quad \dots (1)$$

$$\text{Vertical: } T_1 \cos \theta - T_2 \cos \theta = mg, \quad T_1 - T_2 = \frac{mg}{\cos \theta} = \frac{2mgl}{h} \quad \dots (2)$$

$$\frac{(1)+(2)}{2} : \boxed{T_1 = \frac{ml}{2} \left( \omega^2 + \frac{2g}{h} \right)}, \quad \frac{(1)-(2)}{2} : \boxed{T_2 = \frac{ml}{2} \left( \omega^2 - \frac{2g}{h} \right)}, \quad \boxed{\frac{T_1}{T_2} = \frac{\omega^2 h + 2g}{\omega^2 h - 2g} = \frac{l\omega^2 \cos \theta + g}{l\omega^2 \cos \theta - g}}$$

When  $\omega^2 \geq \frac{2g}{h}$ ,  $T_2 \geq 0$  and the second string will be taut.

$$\text{Tensions in terms of } \theta: \because h = 2l \cos \theta, \quad \therefore \boxed{T_1 = \frac{m}{2} \left( l\omega^2 + \frac{g}{\cos \theta} \right)}, \quad \boxed{T_2 = \frac{m}{2} \left( l\omega^2 - \frac{g}{\cos \theta} \right)}$$

Analysis: Since  $P$  and  $B$  are fixed,  $l, h$  and  $\theta$  are constants. So the faster the angular speed, the higher the value of  $\omega^2$  and therefore higher tension on the strings ( $T_1$  and  $T_2$ ). While  $T_1$  is always positive,  $T_2$  can be negative numerically, which means the lower string is not taut. In such case, the configuration becomes a Conical Pendulum. If the strings are replaced by sticks, when  $T_2$  is negative, the lower stick has an inward compress force in it.

**Equal Length & Collar:** Let  $l = l_1 = l_2$ , and  $\theta = \theta_1 = \theta_2$ ;  $P$  is fixed, but  $B$  is a loose collar of mass  $M$ .

For  $P$ , the previous formulae of a fixed  $B$  still hold.

$$\text{For a loose } B \text{ with mass } M, \text{ its vertical balance is } T_2 \cos \theta = Mg, \quad T_2 = \frac{Mg}{\cos \theta} = \frac{2Mgl}{h} \quad \dots (3)$$

$$\text{Compare with the } T_2 \text{ formula before: } \frac{2Mgl}{h} = \frac{ml}{2} \cdot \left( \omega^2 - \frac{2g}{h} \right), \quad \frac{2Mgl}{h} = \frac{ml\omega^2}{2} - \frac{mgl}{h},$$

$$\frac{g}{h} (2M + m) = \frac{m\omega^2}{2}, \quad \frac{\omega^2 h}{2g} = \frac{2M + m}{m} = \frac{2M}{m} + 1 \quad \dots (4) \quad \boxed{\frac{M}{m} = \frac{1}{2} \left( \frac{\omega^2 h}{2g} - 1 \right)}$$

$$\text{From (2): } mg = T_1 \cos \theta - T_2 \cos \theta = T_1 \cos \theta - Mg, \quad T_1 \cos \theta = (M + m)g, \quad \frac{T_1 \cos \theta}{T_2 \cos \theta} = \frac{(M + m)g}{Mg}$$

$$\therefore \boxed{\frac{T_1}{T_2} = \frac{M + m}{M}} = 1 + \frac{m}{M} = 1 + 2 \cdot \frac{2g}{\omega^2 h - 2g} = \frac{\omega^2 h - 2g + 4g}{\omega^2 h - 2g} = \frac{\omega^2 h + 2g}{\omega^2 h - 2g} \quad (\text{same as before})$$

$$\text{From (3): } T_2 = \frac{2Mgl}{h} = Ml\omega^2 \cdot \frac{2g}{\omega^2 h}, \quad \boxed{T_2 = \frac{Ml\omega^2}{\frac{2M}{m} + 1}}, \quad T_1 = T_2 \cdot \frac{M + m}{M}, \quad \boxed{T_1 = \frac{(M + m)l\omega^2}{\frac{2M}{m} + 1}}$$

**Loose Ring of Mass:**  $B$  is fixed and  $P$  is a ring threaded loosely on the string, so  $T = T_1 = T_2$ .

$$r = l_1 \sin \theta_1 = l_2 \sin \theta_2, \quad h = l_1 \cos \theta_1 + l_2 \cos \theta_2.$$

Horizontal:  $T \sin \theta_1 + T \sin \theta_2 = T(\sin \theta_1 - \sin \theta_2) = mr\omega^2 \quad \dots (5)$

Vertical:  $T \cos \theta_1 - T \cos \theta_2 = T(\cos \theta_1 - \cos \theta_2) = mg \quad \dots (6)$

$$(6) \div (5) : \frac{g}{r\omega^2} = \frac{\cos \theta_1 - \cos \theta_2}{\sin \theta_1 + \sin \theta_2} = \frac{-2 \sin \left( \frac{\theta_1 + \theta_2}{2} \right) \sin \left( \frac{\theta_1 - \theta_2}{2} \right)}{2 \sin \left( \frac{\theta_1 + \theta_2}{2} \right) \cos \left( \frac{\theta_1 - \theta_2}{2} \right)} = -\tan \left( \frac{\theta_1 - \theta_2}{2} \right), \quad \boxed{\tan \left( \frac{\theta_2 - \theta_1}{2} \right) = \frac{g}{r\omega^2}}$$

From (5):  $mr\omega^2 = T \sin \theta_1 + T \sin \theta_2 = T \left( \frac{r}{l_1} + \frac{r}{l_2} \right) = Tr \left( \frac{l_2 + l_1}{l_1 l_2} \right), \quad \boxed{T = m\omega^2 \frac{l_1 l_2}{L}}$