

MMAN2300 2013-10-05 Assignment C

Given: $m_P=440$ g, $R=42$ mm, $H=38$ mm, $L=147$ mm, $m_R=470$ g, $\bar{I}_R=1.75$ gm².

$$\omega_{AB}=3500 \text{ rpm}=3500 \times \frac{2\pi}{60} = 366.52 \text{ rad/s.}$$

$$\frac{L}{R} = 3.5, \quad \left(\frac{L}{R}\right)^2 = 12.25, \quad \frac{R}{L} = 0.2857, \quad \left(\frac{R}{L}\right)^2 = 0.08163, \quad L - H = 0.109, \quad \frac{H}{L} = 0.2585.$$

$$\sin \phi = \frac{R}{L} \cos \theta, \quad \cos \phi = \sqrt{1 - \left(\frac{R}{L}\right)^2 \cos^2 \theta} = \frac{\sqrt{L^2 - R^2 \cos^2 \theta}}{L}.$$

$$\omega_{BC} = \frac{-\omega_{AB} \sin \theta}{\sqrt{\left(\frac{L}{R}\right)^2 - \cos^2 \theta}} = \frac{-R\omega_{AB} \sin \theta}{\sqrt{L^2 - R^2 \cos^2 \theta}} = \frac{-R\omega_{AB} \sin \theta}{L \cos \phi} = \frac{-\omega_{AB} \sin \phi \sin \theta}{\cos \theta \cos \phi} = -\omega_{AB} \tan \phi \tan \theta.$$

$$\begin{aligned} \alpha_{BC} &= \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} \cdot \omega_{AB}^2 = \frac{(R^2 - L^2)R \cos \theta}{(L^2 - R^2 \cos^2 \theta)^{\frac{3}{2}}} \cdot \omega_{AB}^2 = \frac{(R^2 - L^2)R \cos \theta}{L^3 \cos^3 \phi} \cdot \omega_{AB}^2 \\ &= \frac{(R^2 - L^2) \sin \phi}{L^2 \cos^3 \phi} \cdot \omega_{AB}^2 = \left[\left(\frac{R}{L}\right)^2 - 1\right] \frac{\omega_{AB}^2 \tan \phi}{\cos^2 \phi}. \end{aligned}$$

$$v_{C_y} = R \cos \theta (\omega_{AB} - \omega_{BC}).$$

$$\begin{aligned} a_{C_y} &= -R\omega_{AB}^2 \left\{ \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos^2 \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} + \frac{\sin^2 \theta}{\sqrt{\left(\frac{L}{R}\right)^2 - \cos^2 \theta}} + \sin \theta \right\} \\ &= -R\omega_{AB}^2 \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos^2 \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} - R\omega_{AB}^2 \frac{\sin^2 \theta}{\sqrt{\left(\frac{L}{R}\right)^2 - \cos^2 \theta}} - R\omega_{AB}^2 \sin \theta \\ &= -R\alpha_{BC} \cos \theta + R\omega_{AB}\omega_{BC} \sin \theta - R\omega_{AB}^2 \sin \theta \\ &= -R\alpha_{BC} \cos \theta + R\omega_{AB}(\omega_{BC} - \omega_{AB}) \sin \theta \\ &= -R\alpha_{BC} \cos \theta - v_{C_y} \omega_{AB} \tan \theta \end{aligned}$$

- c) Determine the horizontal and vertical forces acting on the connecting rod at points B and C as functions of crank angle.

F_B provides the centripetal force on B towards A and the force pushing the bottom end of the rod around.

F_C is the result of the force from the left wall in the \mathbf{i} direction, and the weight of the piston in the $-\mathbf{j}$ direction.

These are the only two forces acting on the connecting rod.

$$-F_{C_y} - m_P g = m_P a_{C_y}.$$

$$\boxed{F_{C_y} = -m_P a_{C_y} - m_P g.} \quad \text{Generally, } g + a_{C_y} > 0. \text{ So } F_{C_y} < 0 \text{ (downward).}$$

The centre of gravity D divides the rod into CD and DB in the ratio of $L - H : H$.

$$r_D = \frac{H}{L} r_C + \frac{L - H}{L} r_B, \quad v_D = \frac{H}{L} v_C + \frac{L - H}{L} v_B, \quad a_D = \frac{H}{L} a_C + \frac{L - H}{L} a_B.$$

$$a_C = \mathbf{j} a_{C_y}, \quad r_B = R(\mathbf{i} \cos \theta + \mathbf{j} \sin \theta), \quad v_B = R\omega_{AB}(-\mathbf{i} \sin \theta + \mathbf{j} \cos \theta), \quad a_B = -R\omega_{AB}^2(\mathbf{i} \cos \theta + \mathbf{j} \sin \theta).$$

$$a_D = \frac{H}{L} \mathbf{j} a_{C_y} - \frac{L - H}{L} R\omega_{AB}^2(\mathbf{i} \cos \theta + \mathbf{j} \sin \theta) = -\mathbf{i} \frac{L - H}{L} R\omega_{AB}^2 \cos \theta + \mathbf{j} \left(\frac{H}{L} a_{C_y} - \frac{L - H}{L} R\omega_{AB}^2 \sin \theta \right).$$

Alternatively, $a_D = a_C + \alpha_{BC} \times r_{D/C} - \omega_{BC}^2 \cdot r_{D/C}$

$$\begin{aligned}
&= \mathbf{j}a_{C_y} + \mathbf{k} \alpha_{BC} \times [\mathbf{i}(L-H) \sin \phi - \mathbf{j}(L-H) \cos \phi] - \omega_{BC}^2 \cdot [\mathbf{i}(L-H) \sin \phi - \mathbf{j}(L-H) \cos \phi] \\
&= \mathbf{j}a_{C_y} + \alpha_{BC} \cdot [\mathbf{j}(L-H) \sin \phi + \mathbf{i}(L-H) \cos \phi] - \omega_{BC}^2 \cdot [\mathbf{i}(L-H) \sin \phi - \mathbf{j}(L-H) \cos \phi]. \\
&= \mathbf{j}a_{C_y} + \alpha_{BC} \mathbf{j}(L-H) \sin \phi + \alpha_{BC} \mathbf{i}(L-H) \cos \phi - \omega_{BC}^2 \mathbf{i}(L-H) \sin \phi + \omega_{BC}^2 \mathbf{j}(L-H) \cos \phi. \\
&= \mathbf{i} [\alpha_{BC}(L-H) \cos \phi - \omega_{BC}^2(L-H) \sin \phi] + \mathbf{j} [a_{C_y} + \alpha_{BC}(L-H) \sin \phi + \omega_{BC}^2(L-H) \cos \phi].
\end{aligned}$$

This can be proven to be equivalent to a_D above.

$$F_{B_y} + F_{C_y} - m_R g = m_R a_{D_y}.$$

$$\begin{aligned}
F_{B_y} &= m_R a_{D_y} + m_R g - F_{C_y} = m_R a_{D_y} + m_R g + m_P g + m_P a_{C_y} \\
&= m_R [a_{C_y} + \alpha_{BC}(L-H) \sin \phi + \omega_{BC}^2(L-H) \cos \phi] + m_R g + m_P g + m_P a_{C_y} \\
&= (m_R + m_P)(a_{C_y} + g) + m_R [\alpha_{BC}(L-H) \sin \phi + \omega_{BC}^2(L-H) \cos \phi] \\
&= (m_R + m_P)(a_{C_y} + g) + m_R \left[\frac{(R^2 - L^2) \sin \phi}{L^2 \cos^3 \phi} \cdot \omega_{AB}^2 \cdot (L-H) \sin \phi + \frac{R^2 \omega_{AB}^2 \sin^2 \theta}{L^2 \cos^2 \phi} (L-H) \cos \phi \right] \\
&= (m_R + m_P)(a_{C_y} + g) + \frac{m_R \omega_{AB}^2 (L-H)}{L^2 \cos^2 \phi} \left[(R^2 - L^2) \frac{\sin^2 \phi}{\cos \phi} + R^2 \sin^2 \theta \cos \phi \right] \\
&= (m_R + m_P)(a_{C_y} + g) + \frac{m_R \omega_{AB}^2 (L-H)}{L^2 \cos^2 \phi} \left[(R^2 - L^2) \frac{\sin^2 \phi}{\cos \phi} + (R^2 - L^2 \sin^2 \phi) \cos \phi \right] \\
&= (m_R + m_P)(a_{C_y} + g) + \frac{m_R \omega_{AB}^2 (L-H)}{L^2 \cos^3 \phi} [R^2 \sin^2 \phi - L^2 \sin^2 \phi + R^2 \cos^2 \phi - L^2 \sin^2 \phi \cos \phi^2] \\
&= (m_R + m_P)(a_{C_y} + g) + \frac{m_R \omega_{AB}^2 (L-H)}{L^2 \cos^3 \phi} [R^2 - L^2 \sin^2 \phi (1 + \cos \phi^2)]
\end{aligned}$$

FOLLOWINGS ARE UNFINISHED

$$\begin{aligned}
&= m_R \left(-\frac{H}{L} R \omega_{AB}^2 \left\{ \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos^2 \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} + \frac{\sin^2 \theta}{\sqrt{\left(\frac{L}{R}\right)^2 - \cos^2 \theta}} + \sin \theta \right\} - \frac{L-H}{L} R \omega_{AB}^2 \sin \theta \right) + (m_R + m_P)g \\
&= -m_R \frac{H}{L} R \omega_{AB}^2 \left\{ \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos^2 \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} + \frac{\sin^2 \theta}{\sqrt{\left(\frac{L}{R}\right)^2 - \cos^2 \theta}} + \sin \theta + \frac{L-H}{H} \sin \theta \right\} + (m_R + m_P)g
\end{aligned}$$

$$F_{B_y} = -685.5 \left\{ \frac{-11.25 \cos^2 \theta}{[12.25 - \cos^2 \theta]^{\frac{3}{2}}} + \frac{\sin^2 \theta}{\sqrt{12.25 - \cos^2 \theta}} + 3.868 \sin \theta \right\} + 8.927.$$

Moment about B : $-L \sin \phi \cdot F_{C_y} - L \cos \phi \cdot F_{C_x} = (\bar{I}_R + m_R H^2) \alpha_{BC}$.

$$\begin{aligned}
 F_{C_x} &= \frac{(\bar{I}_R + m_R H^2) \alpha_{BC} + L \sin \phi \cdot F_{C_y}}{-L \cos \phi} = \frac{1}{-L \cos \phi} \left[(\bar{I}_R + m_R H^2) \alpha_{BC} - L \frac{R}{L} \cos \theta \cdot m_P g \right], \\
 &= \frac{-1}{\sqrt{L^2 - R^2 \cos^2 \theta}} \left[(\bar{I}_R + m_R H^2) \cdot \frac{\left[1 - \left(\frac{L}{R}\right)^2\right] \cos \theta}{\left[\left(\frac{L}{R}\right)^2 - \cos^2 \theta\right]^{\frac{3}{2}}} \cdot \omega_{AB}^2 - R \cos \theta \cdot m_P g \right] \\
 &= \frac{-R \cos \theta}{\sqrt{L^2 - R^2 \cos^2 \theta}} \left[(\bar{I}_R + m_R H^2) \cdot \frac{(R^2 - L^2)}{(L^2 - R^2 \cos^2 \theta)^{\frac{3}{2}}} \cdot \omega_{AB}^2 - m_P g \right] \\
 &= \frac{-R (\bar{I}_R + m_R H^2) \cdot (R^2 - L^2) \omega_{AB}^2}{(L^2 - R^2 \cos^2 \theta)^2} \cdot \cos \theta + \frac{R m_P g}{\sqrt{L^2 - R^2 \cos^2 \theta}} \cos \theta
 \end{aligned}$$

$$F_{C_x} = \frac{582.3}{(1 - 0.08163 \cos^2 \theta)^2} \cdot \cos \theta + \frac{1.233}{\sqrt{1 - 0.08163 \cos^2 \theta}} \cdot \cos \theta.$$

Horizontal force: $F_{C_x} + F_{B_x} = m_R a_{D_x}$.

$$\begin{aligned}
 F_{B_x} &= m_R a_{D_x} - F_{C_x} = -m_R \frac{L - H}{L} R \omega_{AB}^2 \cos \theta + \frac{R (\bar{I}_R + m_R H^2) \cdot (R^2 - L^2) \omega_{AB}^2}{(L^2 - R^2 \cos^2 \theta)^2} \cdot \cos \theta - \frac{R m_P g}{\sqrt{L^2 - R^2 \cos^2 \theta}} \cos \theta \\
 &= R \omega_{AB}^2 \left[-m_R \frac{L - H}{L} + \frac{(\bar{I}_R + m_R H^2) \cdot (R^2 - L^2)}{(L^2 - R^2 \cos^2 \theta)^2} \right] \cos \theta - \frac{R m_P g}{\sqrt{L^2 - R^2 \cos^2 \theta}} \cos \theta.
 \end{aligned}$$

$$F_{B_x} = -1966 \cos \theta - \frac{582.3}{(1 - 0.08163 \cos^2 \theta)^2} \cos \theta - \frac{1.233}{\sqrt{1 - 0.08163 \cos^2 \theta}} \cos \theta.$$